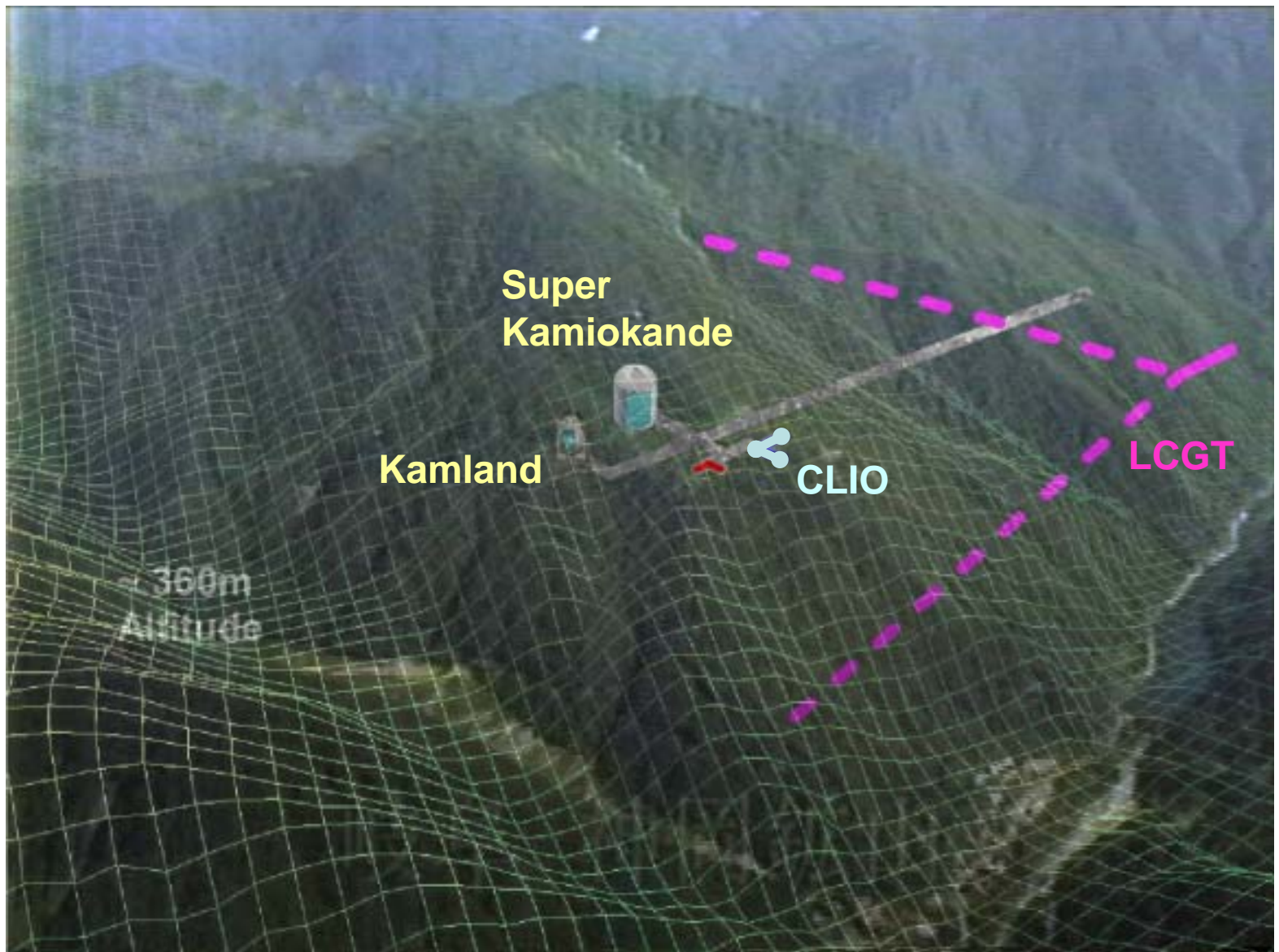


低温レーザー干渉計CLIO(VII)

寺田聡一, 黒田和明, 大橋正健, 三代木伸二, 内山隆, 山元一広, 徳成正雄, 阿久津朋美, 鎌ヶ迫将悟, 中川憲保, 新富孝和, 山本明, 春山富義, 鈴木敏一, 佐藤伸明, 都丸隆行, 竹本修三, 早河秀章, 新谷昌人, 高森昭光, 辰巳大輔, 安東正樹



History of CLIO

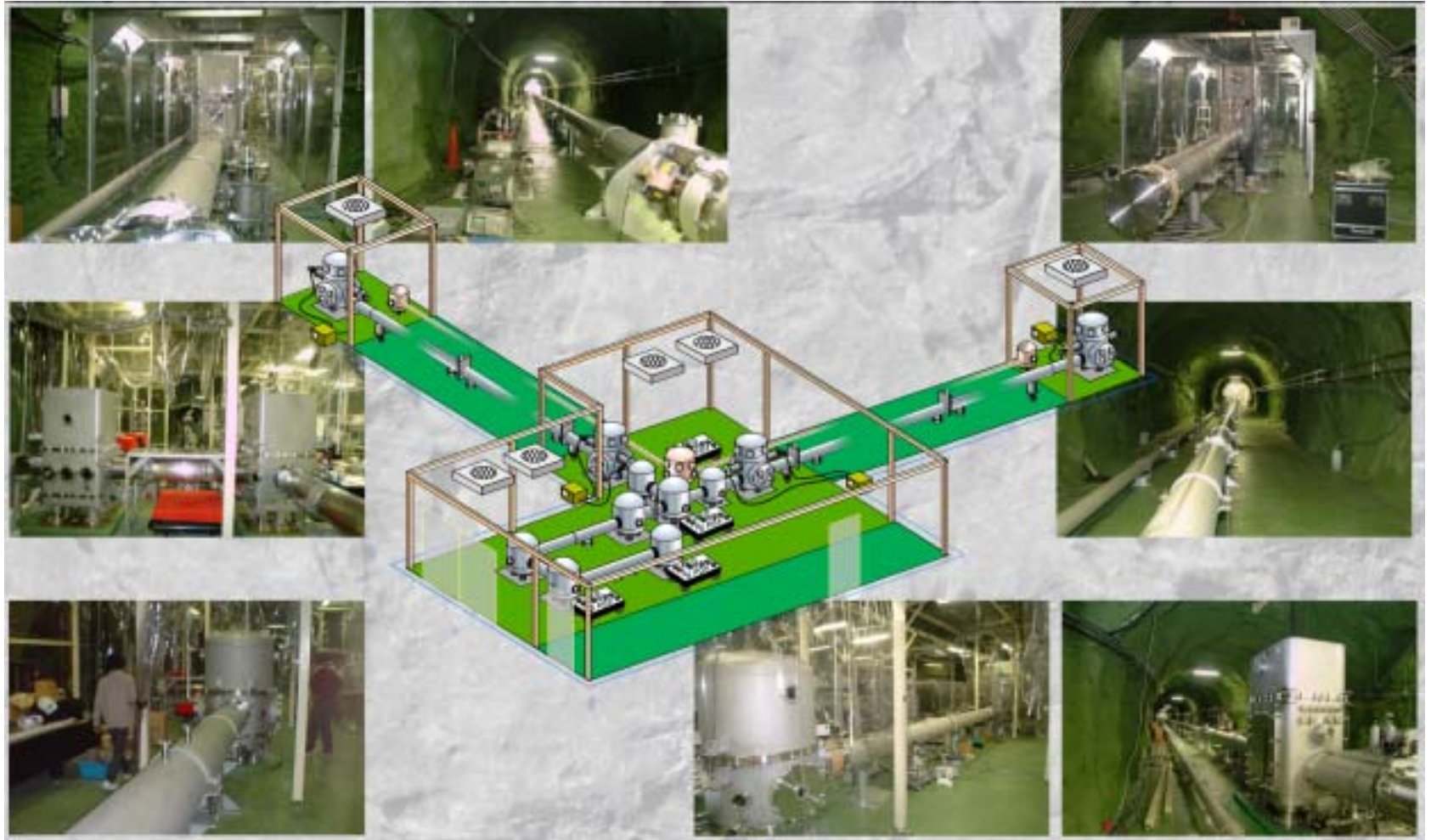
- 2003 Jan. Experimental cave completed
- 2004 Jan. MC vacuum chamber installed
- 2004 Apr. Input optics installed and MC locked
- 2004 Oct. One cryostat installed
- 2005 Mar. Perpendicular arm vacuum system installed
- 2005 May One cryogenic pendulum installed
- 2005 Jun. Inline arm vacuum system installed
- 2005 Jul. Second cryogenic pendulum installed
- 2005 Sep. Inline arm FP experiment started

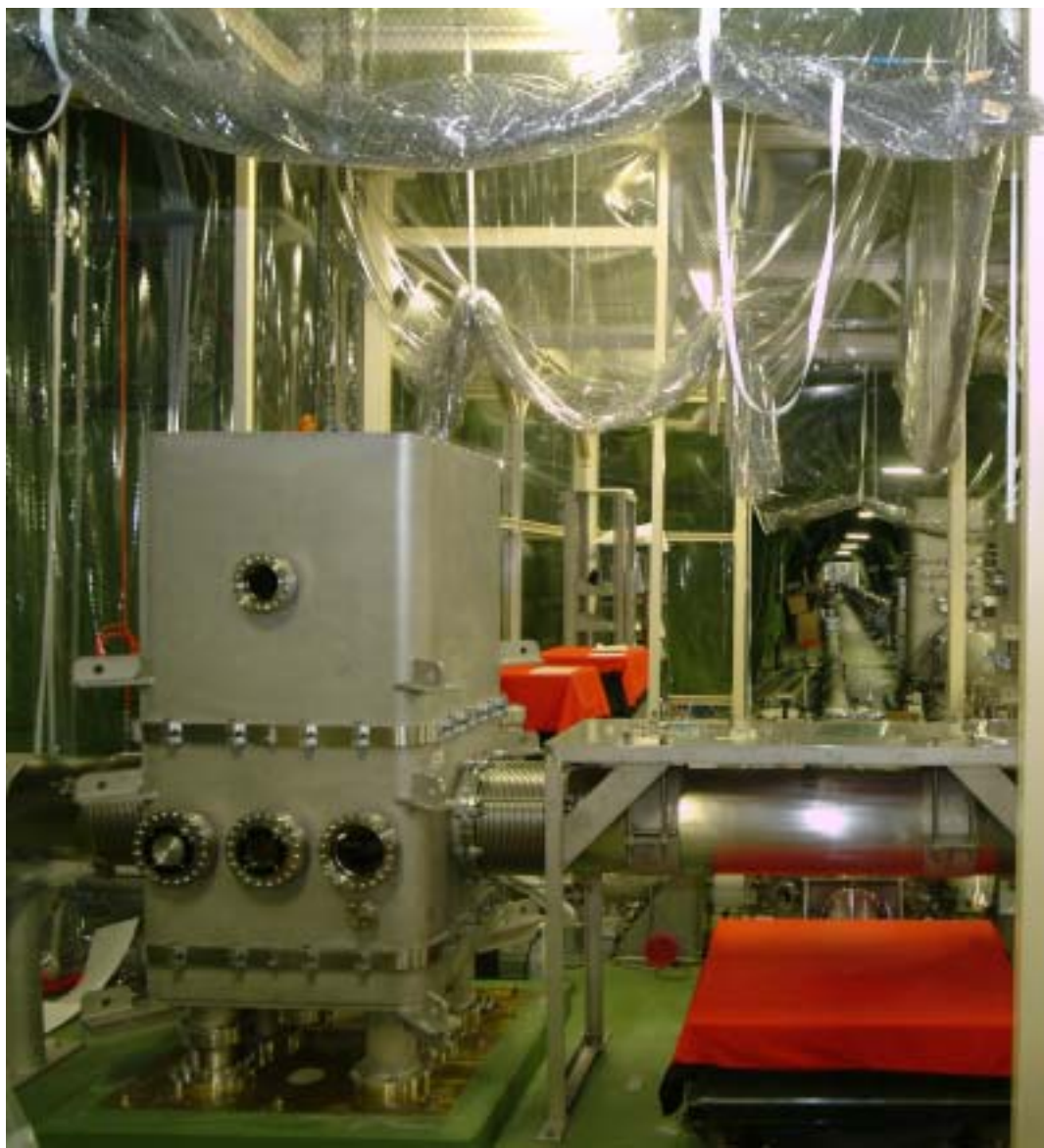


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CLIO Vacuum System

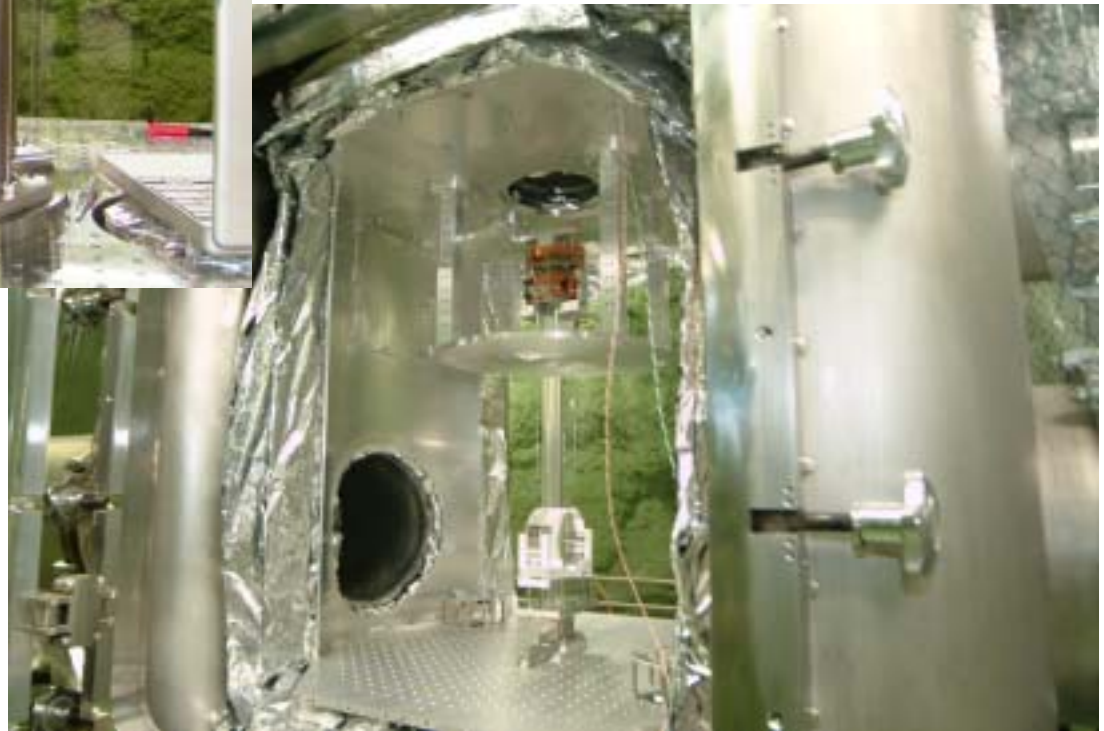
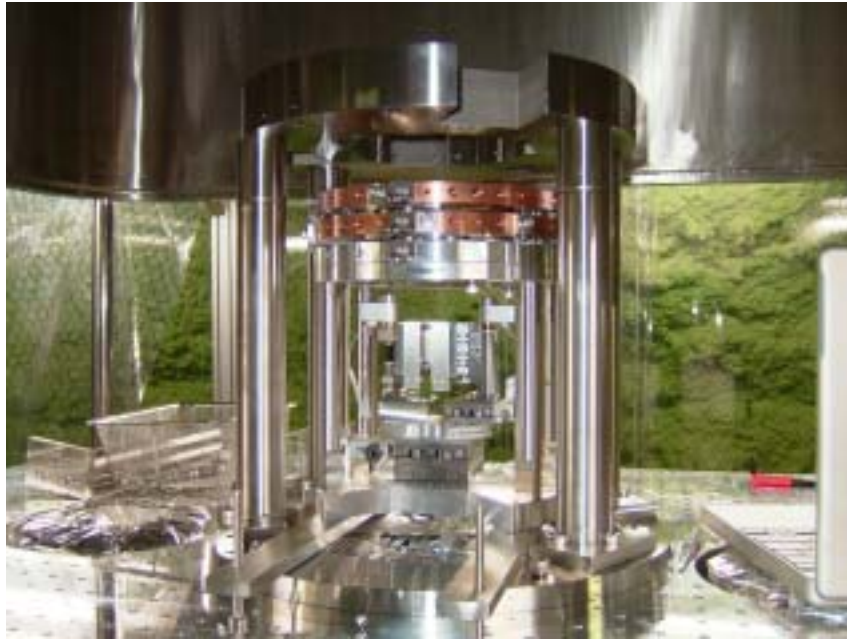




Cryogenic Vacuum Tank



Cryogenic Pendulum



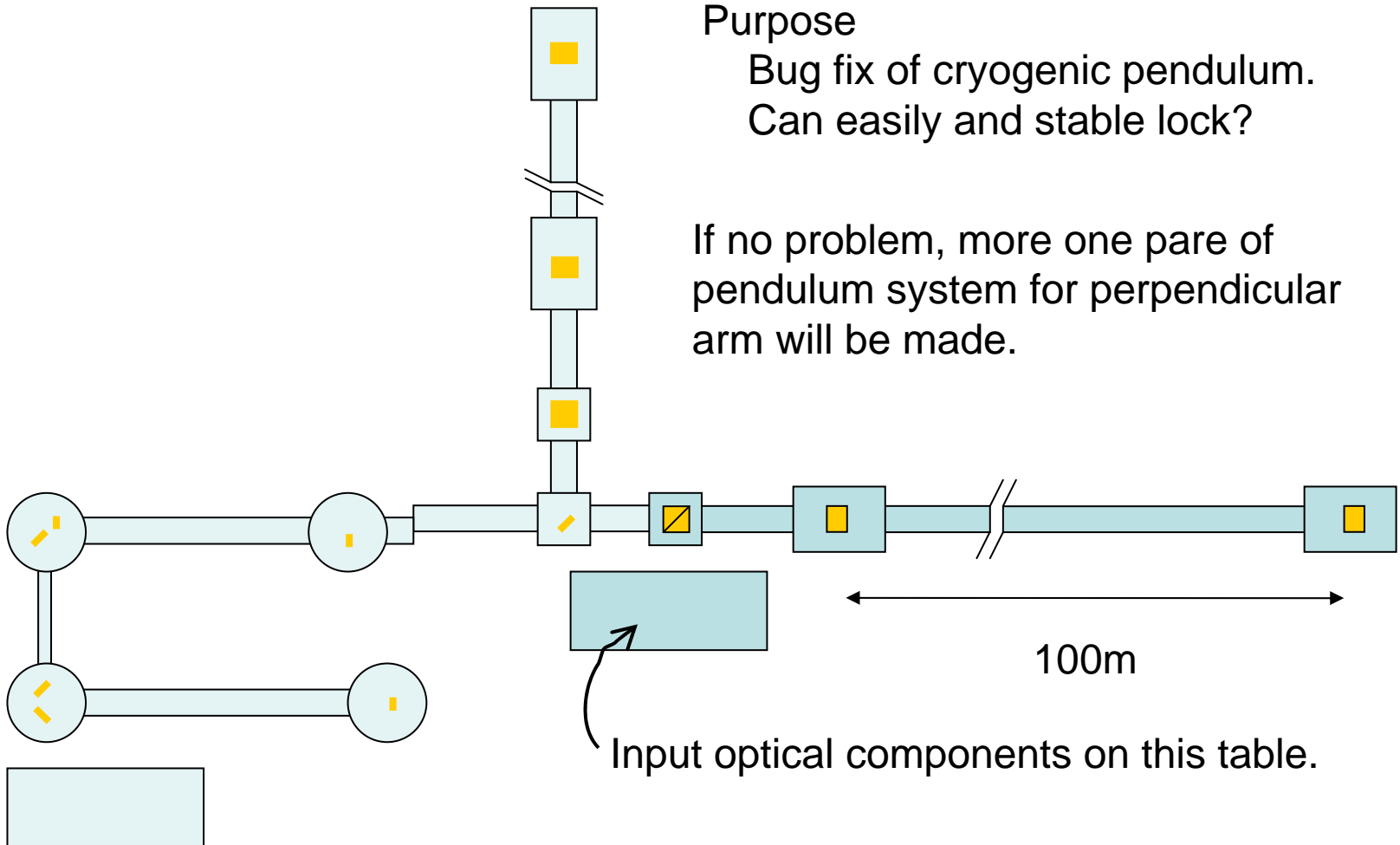
Inline FP Experiment

2005 Sep. Start !!

Purpose

Bug fix of cryogenic pendulum.
Can easily and stable lock?

If no problem, more one pare of
pendulum system for perpendicular
arm will be made.



Summary of Inline FP Experiment

- Input optics have been installed.
- Incident beam achieved to the end mirror and the reflected beam came back to the near mirror chamber without near mirror.
- Since laser power was small (100mW), the transmitted light through the near mirror was lost.
- The mirror has wedge (10 arc min.) (out of our knowledge).
- Will replace to high power laser.
- Will change incident axis for the wedge.