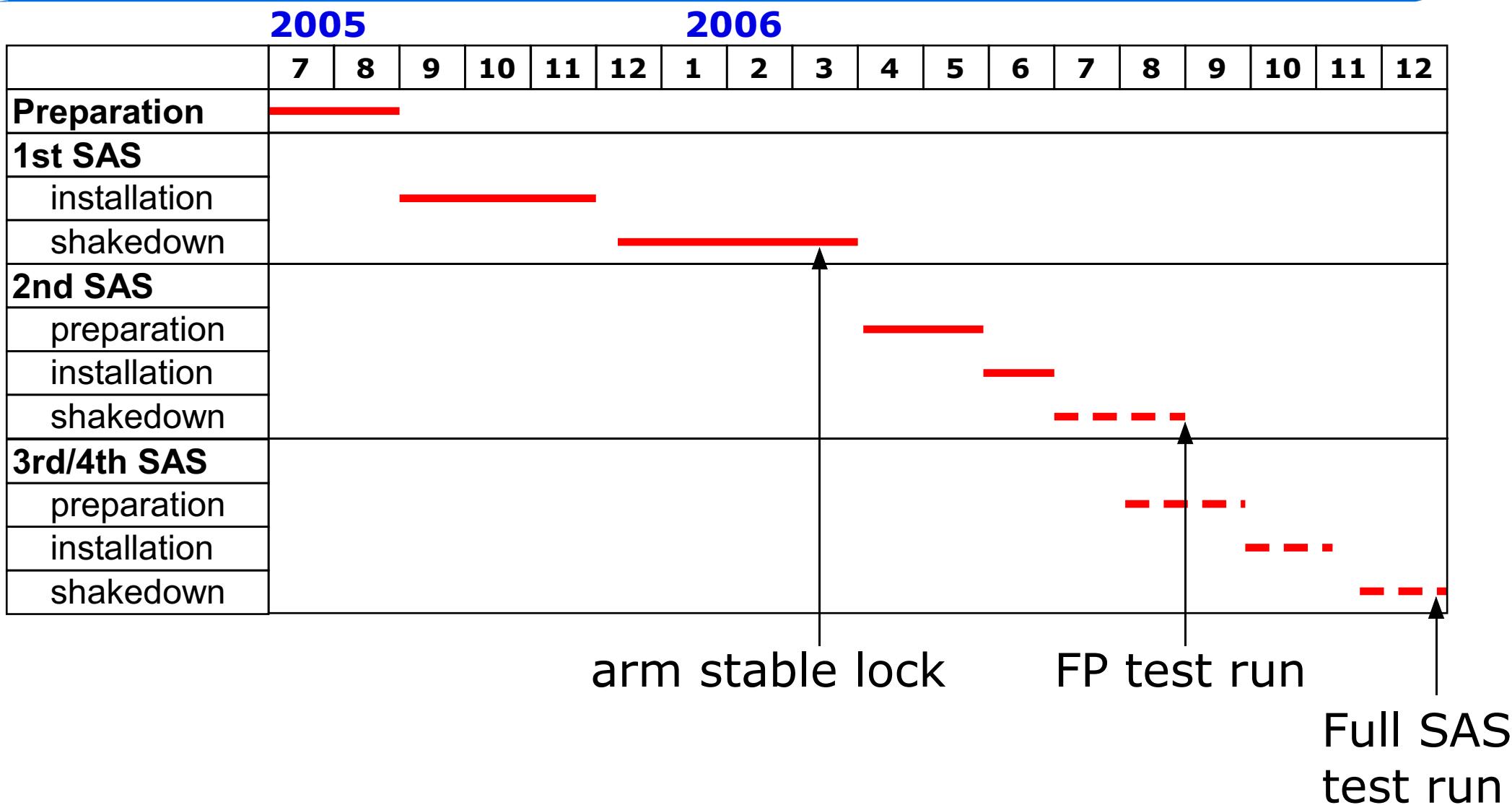


TAMA Status Report

- o SAS Installation
(Takahashi, Agatsuma, Arase +all)
- o Revisiting TAMA (Aso, Tatsumi, Arai)
- o TAMA interferometer work
(Nakagawa, Tatsumi, Arai)

SAS installation status

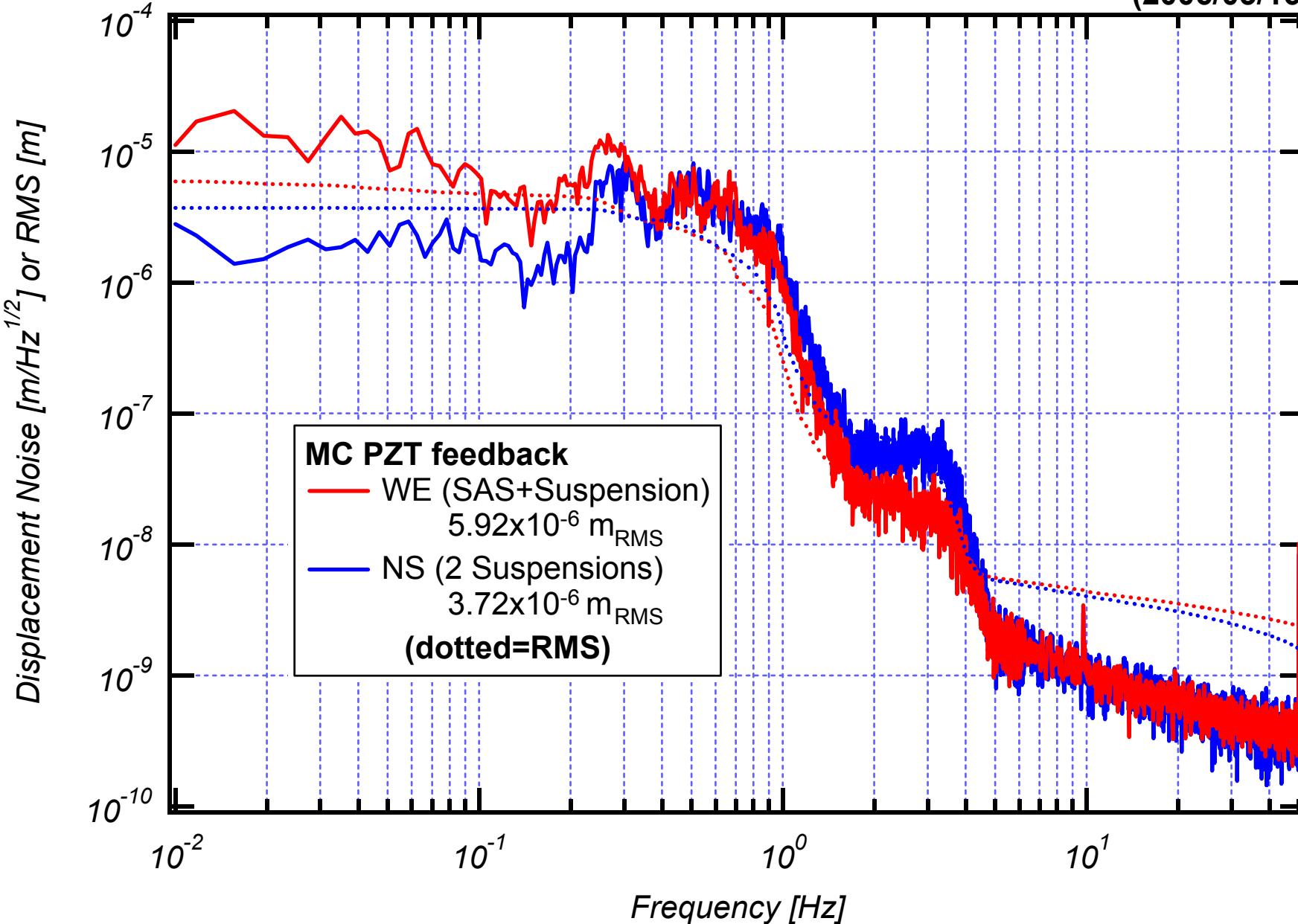


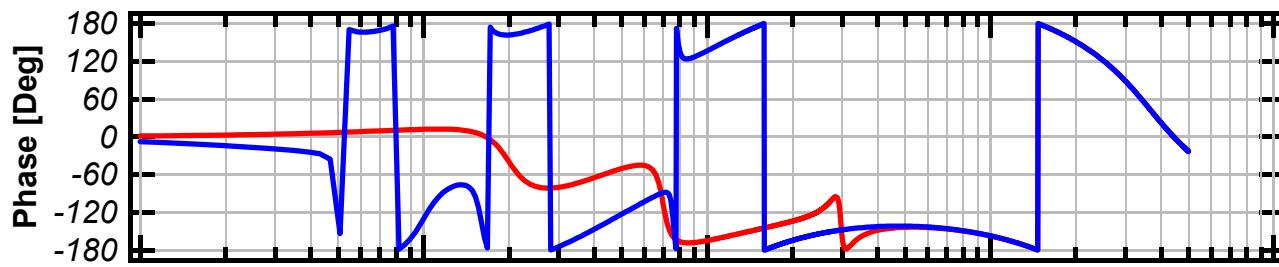
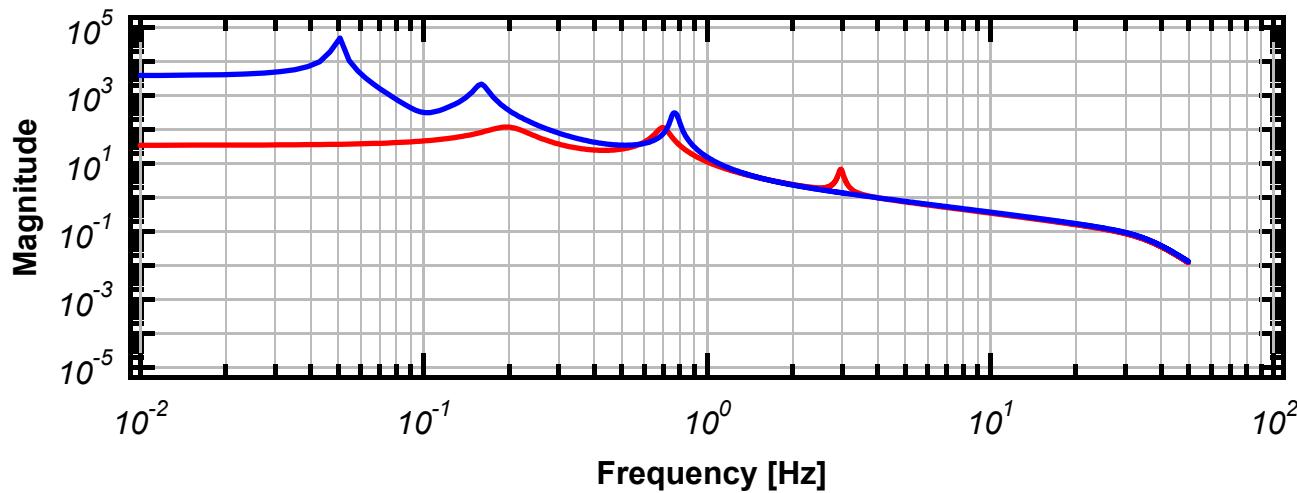
2nd SAS installation



Displacement of FP cavities estimated from MCPZTfb

(2006/03/16)





RMS

Pitch Unstab: 1.84 urad
 Pitch Stab: 0.093 urad

Yaw Unstab: 94.2 urad
 Yaw Stab: 0.10 urad

Pitch:

Actuator Response:

factor -15.9u rad/V
 pole f:2.97 q:26.8
 pole f:1.84 q:3.06
 zero f:1.97 q:2.57

New Filter

pole f:0.2	q:3	resonant gain1p
zero f:0.4	q:0.7	resonant gain1z
pole f:0.7	q:10	pseudo mech. reso.
zero f:2.97	q:5.3	actuator comp. (incomplete)
zero f:1.84	q:3.06	actuator comp.
pole f:1.97	q:2.57	actuator comp.
zero f:1.2		phase compensation
pole f:40		high freq roll-off
pole f:36	q:0.55	4th butterworth1
pole f:36	q:1.3	4th butterworth2

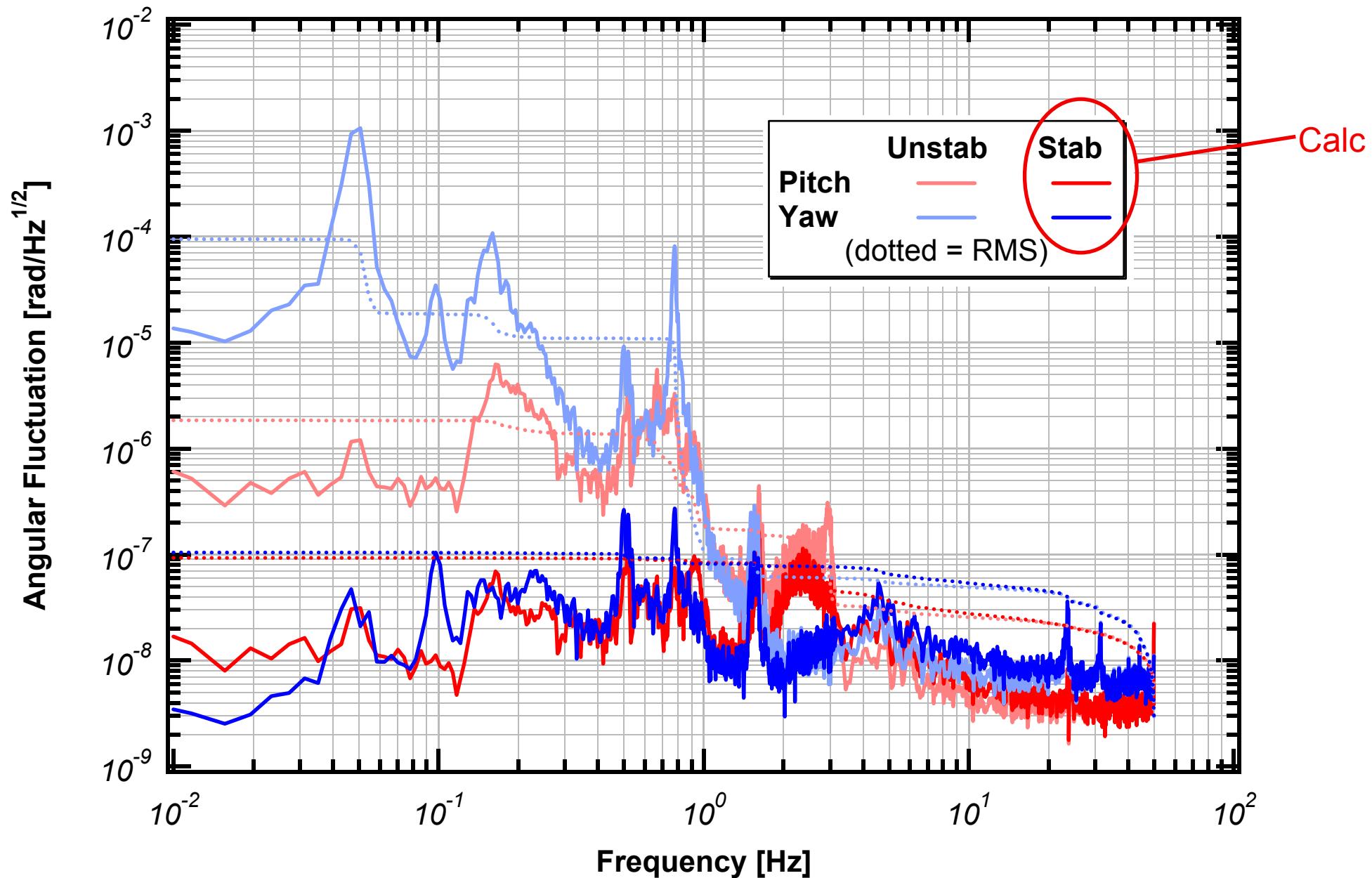
Yaw:

Actuator Response:

factor -289u rad/V
 pole f:0.781 q:19.7
 pole f:0.757 q:22.3
 zero f:0.764 q:12.3

New Filter

pole f:0.05		integrator pair1
pole f:0.05	q:30	resonant gain1p
zero f:0.1	q:3	resonant gain1z
pole f:0.16	q:10	resonant gain2p
zero f:0.4	q:0.7	resonant gain2z
zero f:1.1	q:0.7	phase compensation
pole f:40		high freq roll-off
pole f:36	q:0.55	4th butterworth1
pole f:36	q:1.3	4th butterworth2



TAMA interferometer work

- o Revisiting TAMA (Aso, Tatsumi, Arai)
- o L- improvement plan
- o TAMA mid-time scale improvement plan (Tatsumi)
Target: $dx = 3 \times 10^{-19}$ m/rHz@100Hz

Alignment noise - WFS / beam jitter => MC Alignment
dL- gain distribution Preemphasis/Deemphasis
dl- feedforward 1%
intensity noise reduction
oscillator phase noise reduction / coupling reduction

- o CLIOとの共通技術が多い
共同開発およびCLIO-TAMAへのもしくは逆が望ましい
TAMA->CLIO技術移転、
CLIO->TAMA技術移転